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2024**Force analysis of a soft-rigid hybrid pneumatic actuator and its application in a bipedal inchworm robot.**Jiang Z and Zhang K. *Robotica* 1-17. Cambridge University Press (Cup).**A Wearable Finger Tremor-Suppression Orthosis Using the PVC Gel Linear Actuator.**Liu C and Zhang K. *Ieee Robotics and Automation Letters* vol. PP, (99) 1-8. Institute of Electrical and Electronics Engineers (Ieee).**Underwater Turbid Media Stokes-Based Polarimetric Recovery.**Wang Z, Hu M and Zhang K. *Sensors* vol. 24, (5). Mdpi.**Development of a Pneumatically Actuated Quadruped Robot Using SoftRigid Hybrid Rotary Joints.**Jiang Z, Wang Y and Zhang K. *Robotics* vol. 13, (2). Mdpi.**Author Correction: Aerial additive manufacturing with multiple autonomous robots.**Zhang K, Chermprayong P, Xiao F, Tzoumanikas D, Dams B, Kay S, Kocer BB, Burns A, Orr L, Alhinai T, Choi C, Darekar DD, Li W, Hirschmann S, Soana V, Ngah SA, Grillot C, Sareh S, Choubey A, Margheri L, Pawar VM, Ball RJ, Williams C, Shepherd P, Leutenegger S, Stuart-Smith R and Kovac M. *Nature* vol. 626, (7998) e5-e5. Springer Nature.**2023****Propelling the widespread adoption of large-scale 3D printing.**Zuo Z, Wouter De C, Huang Y, Chen X, Zhang Y, Li J, Zhang L, Xiao J, Yuan Y, Zhang K, Zhang L and Mechtcherine V. *Nature Reviews Materials*. Nature Research.**An Electric SelfSensing and VariableStiffness Artificial Muscle.**Liu C, Busfield JJC and Zhang K. *Advanced Intelligent Systems* vol. 5, (9). Wiley.**IDETC-CIE2023 Front Matter.**

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